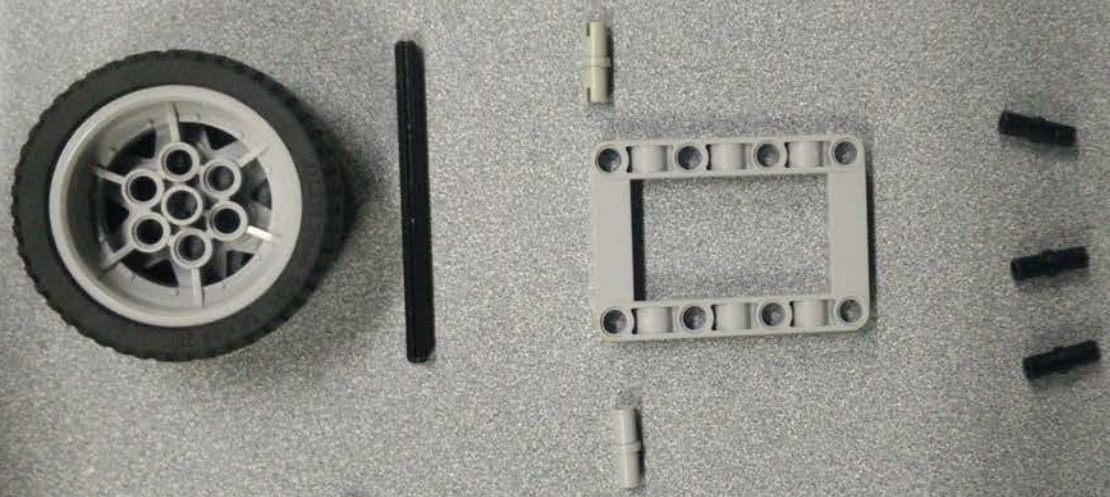
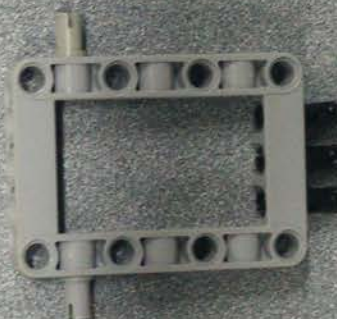




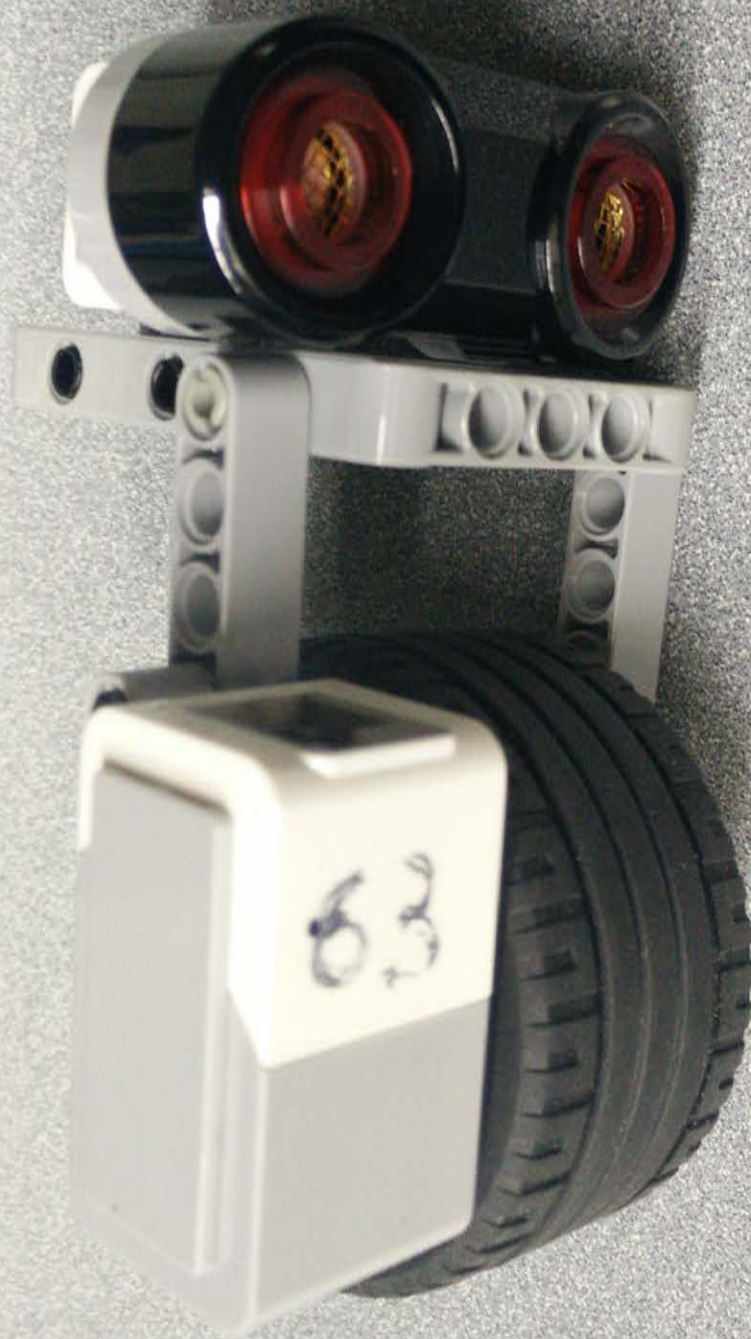






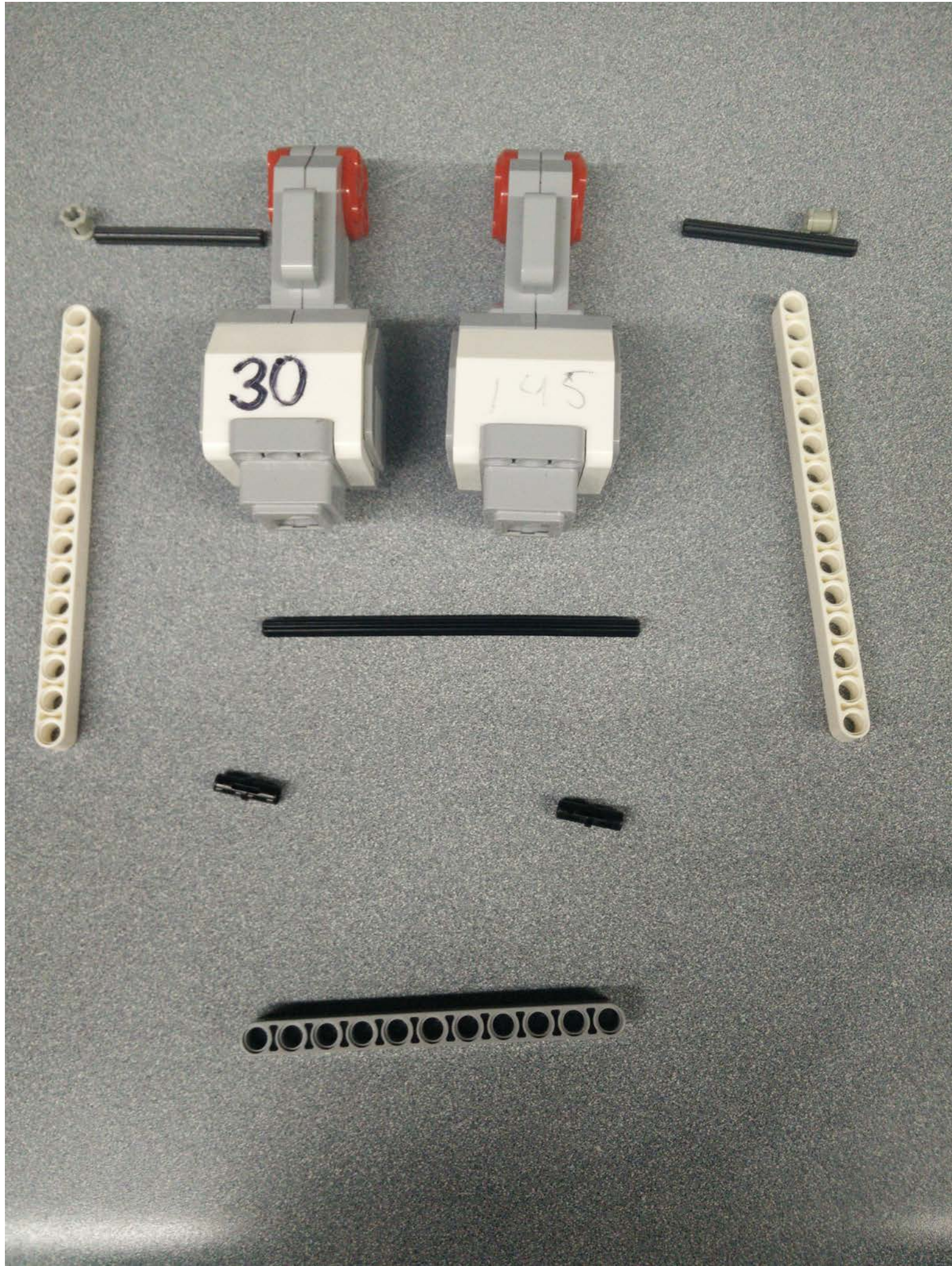


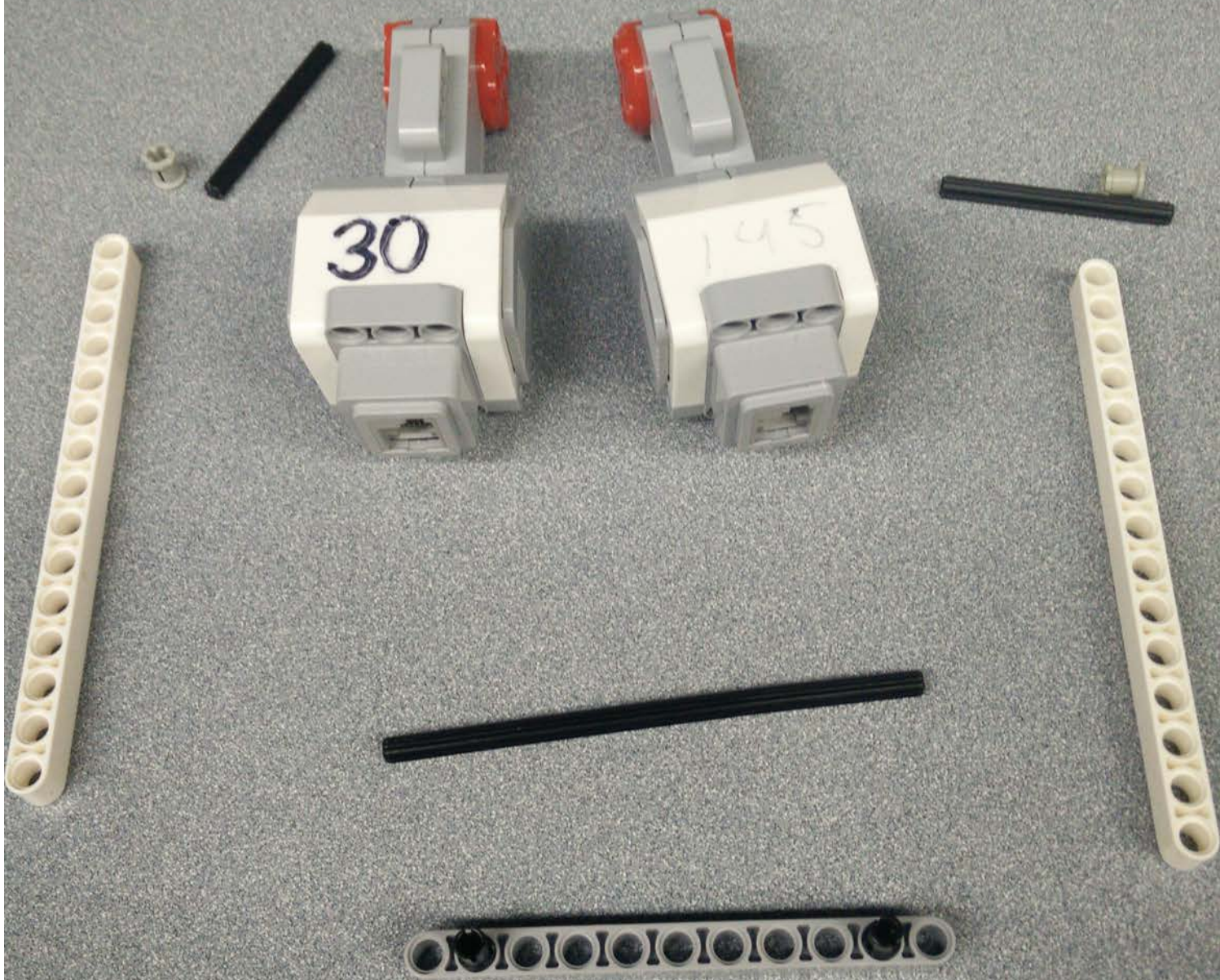


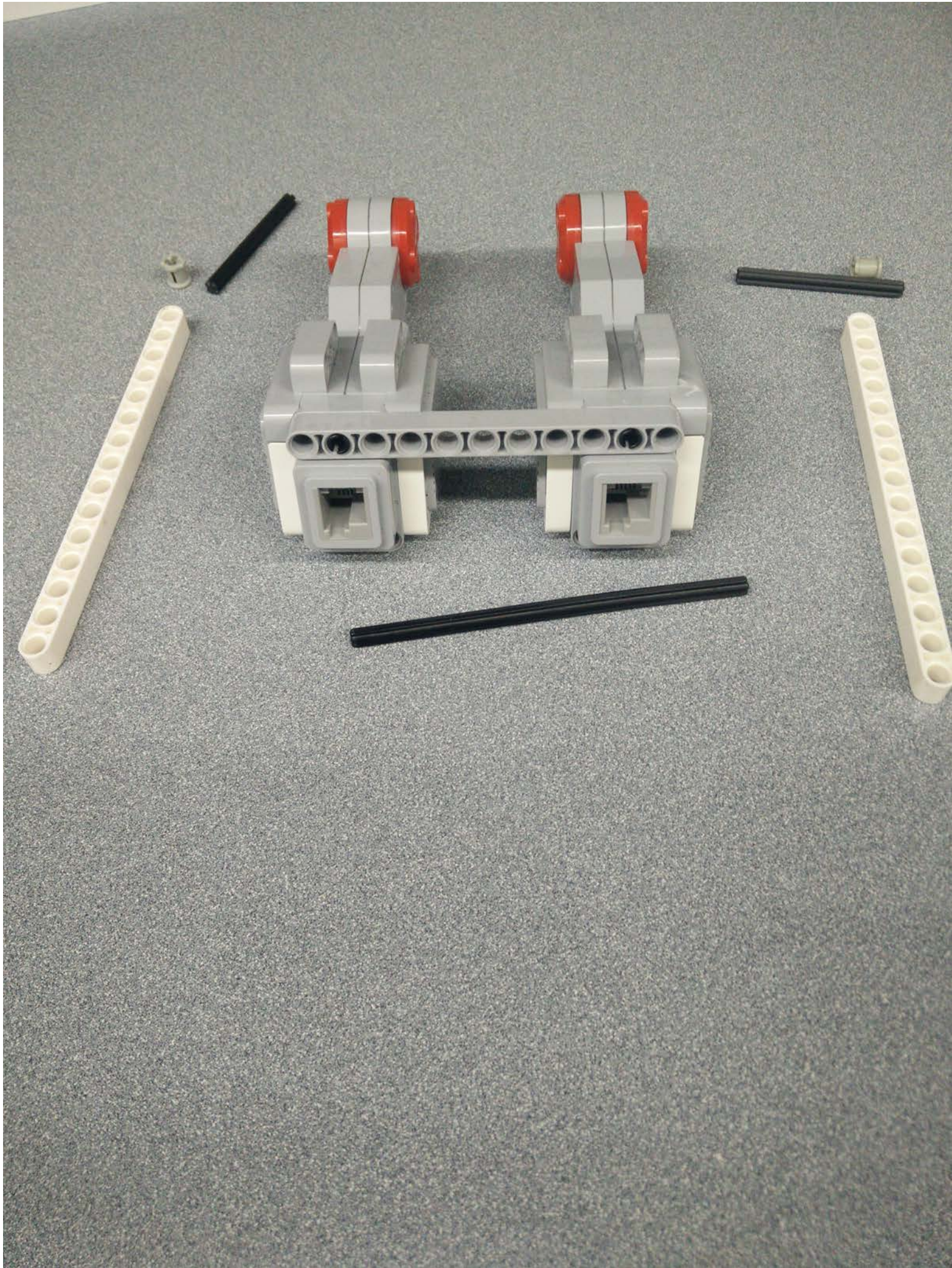


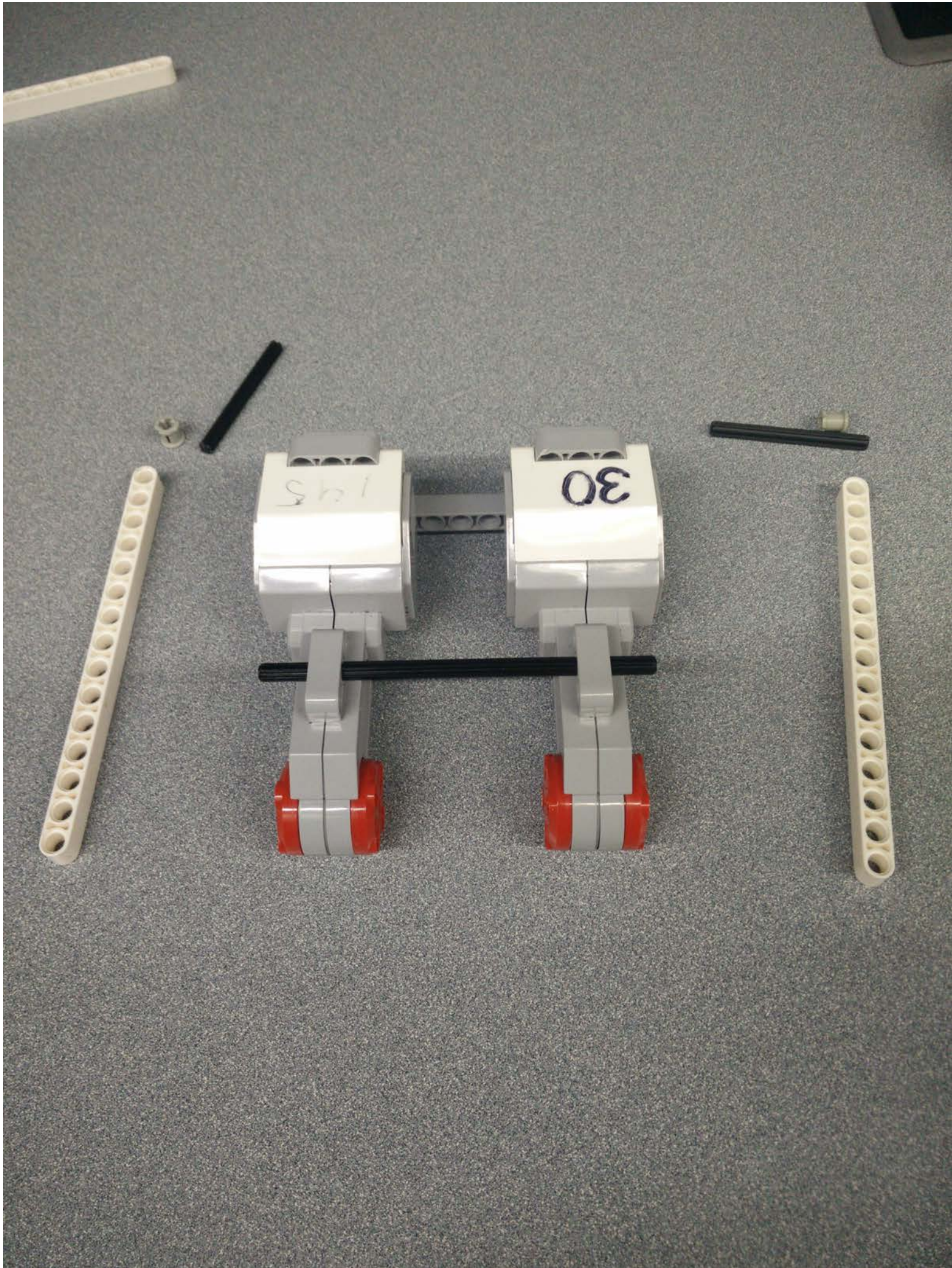


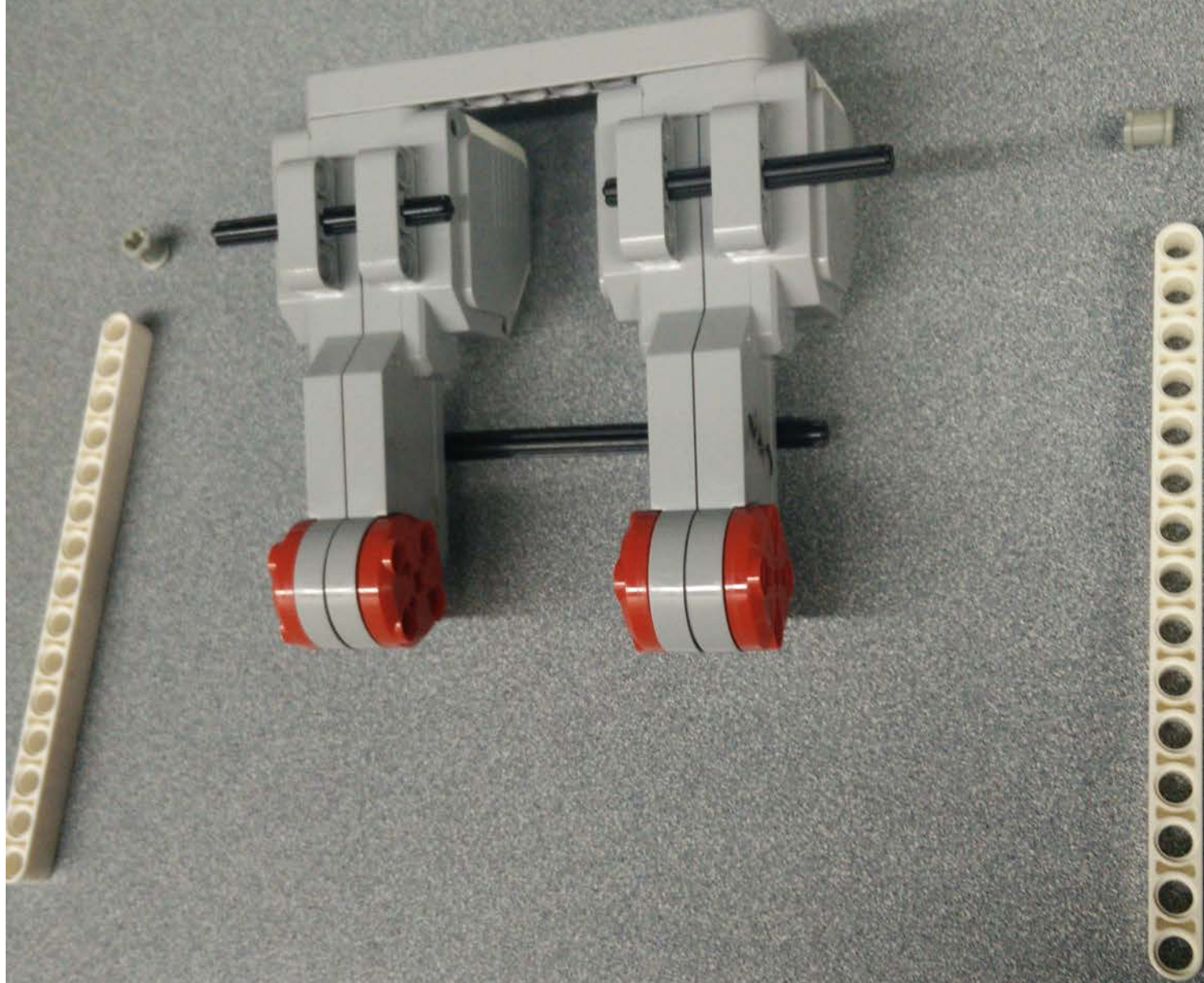


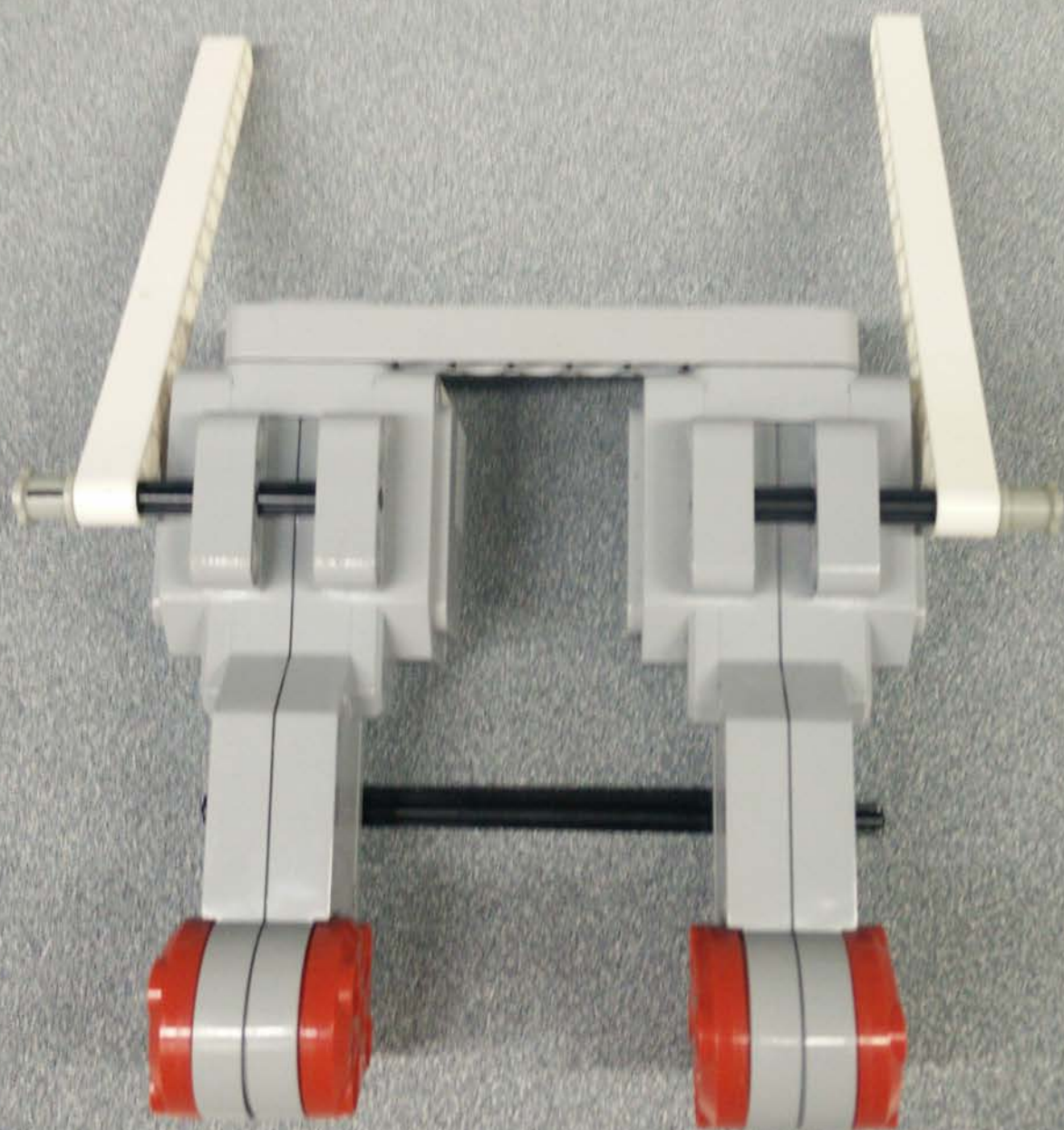


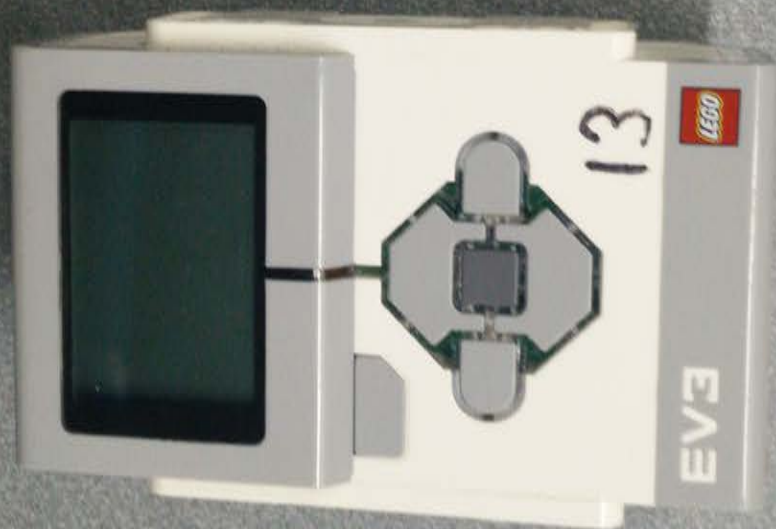


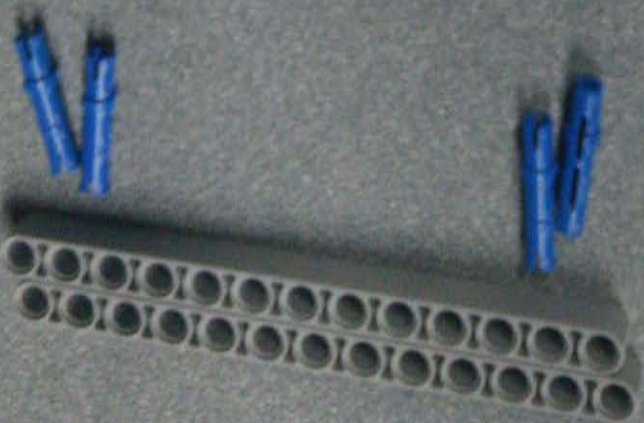


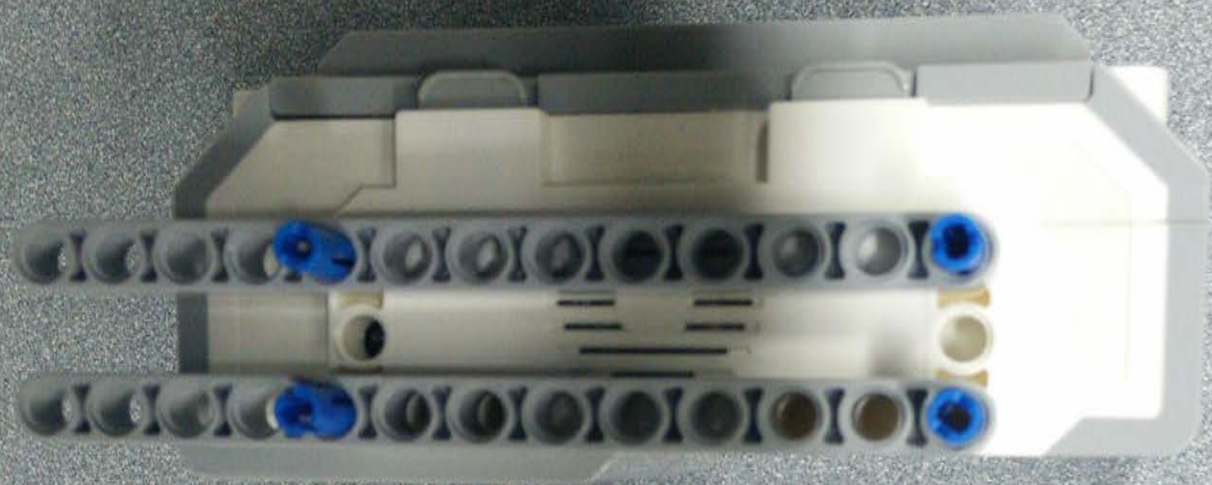


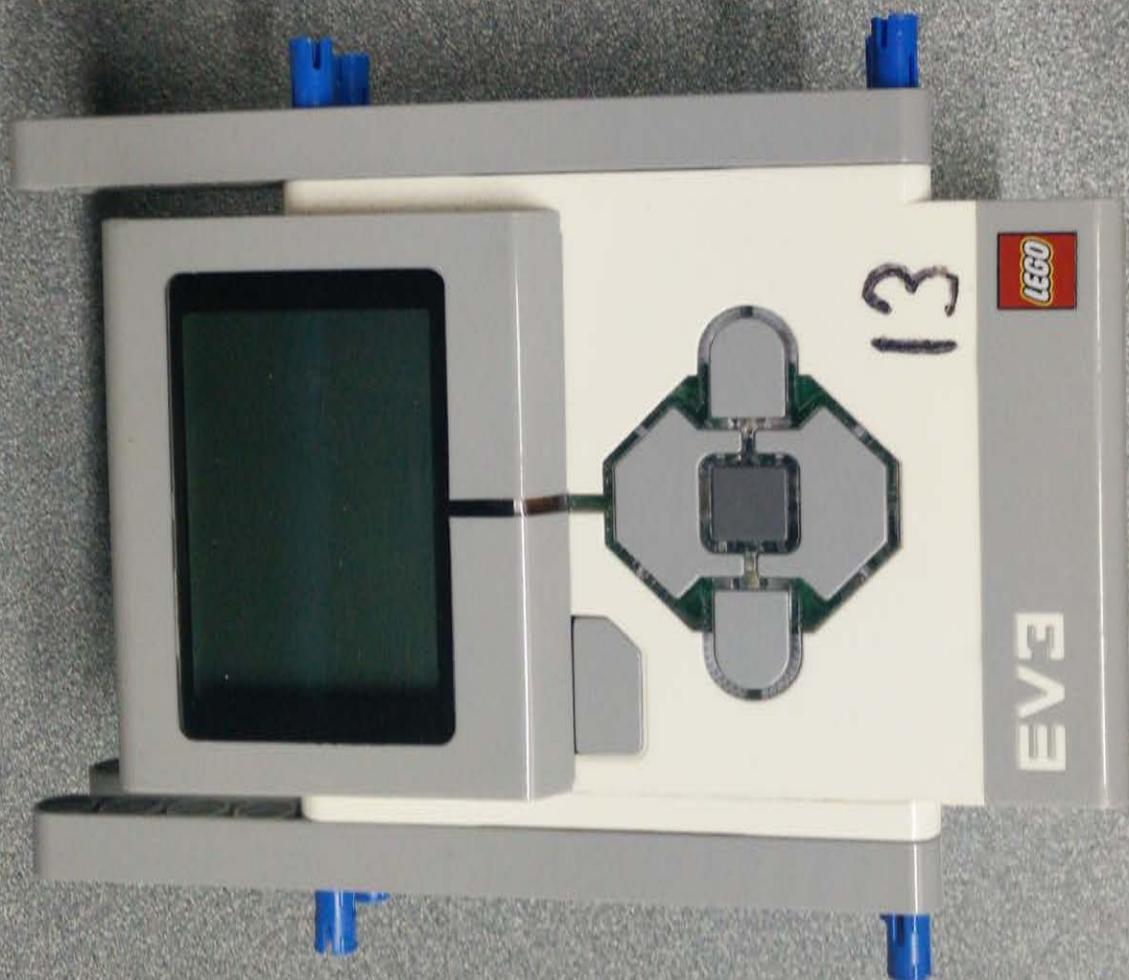


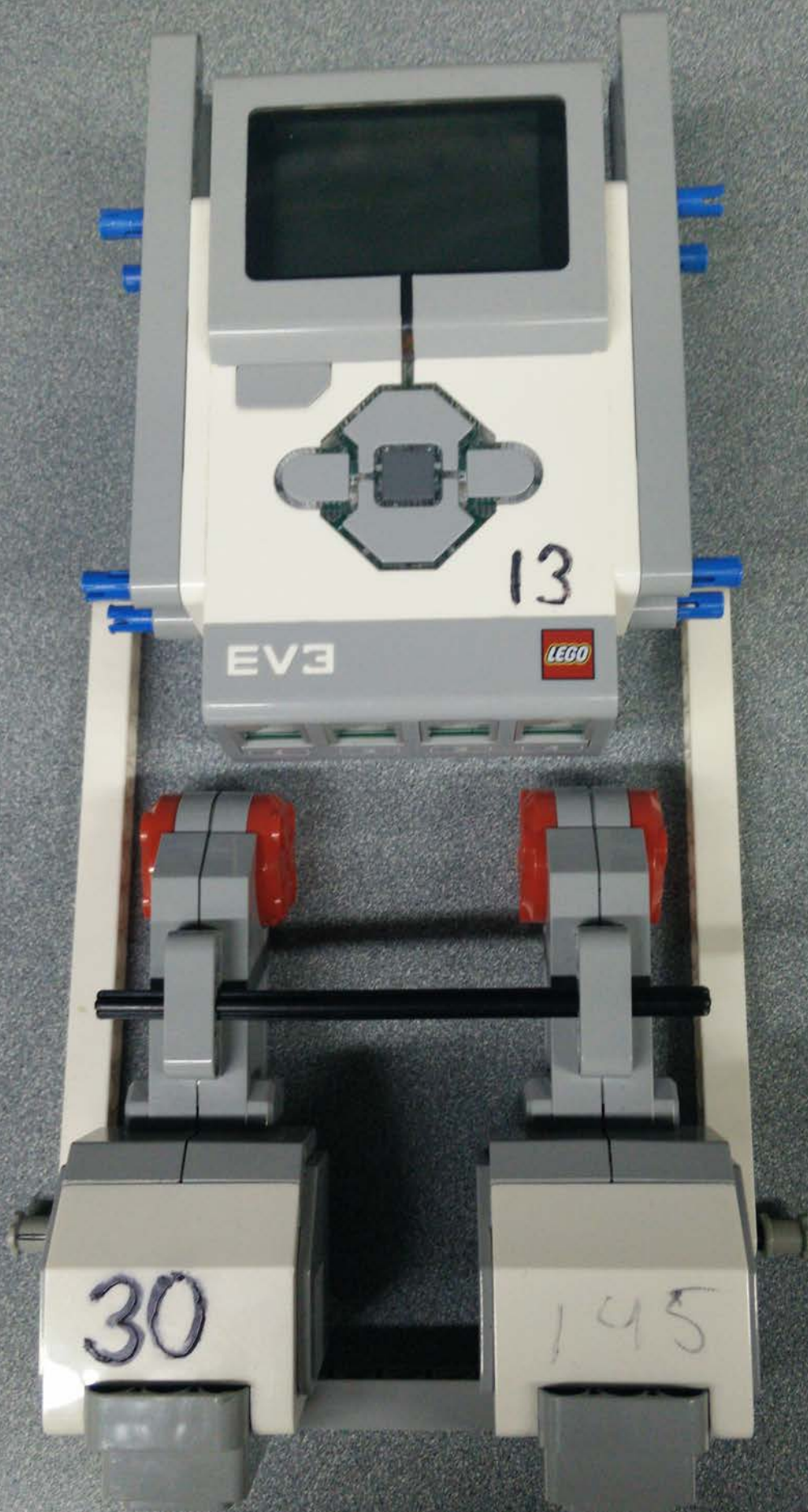




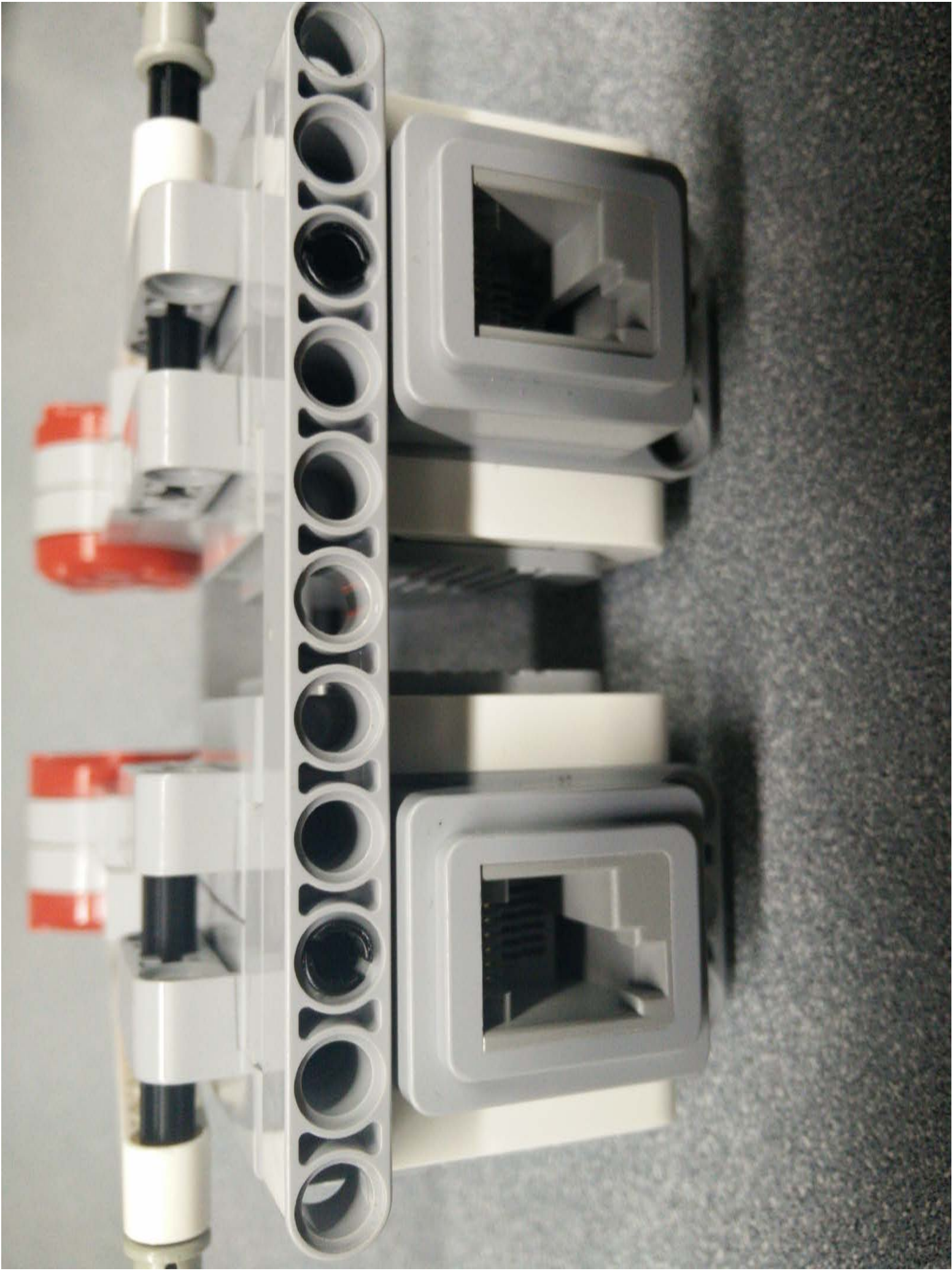




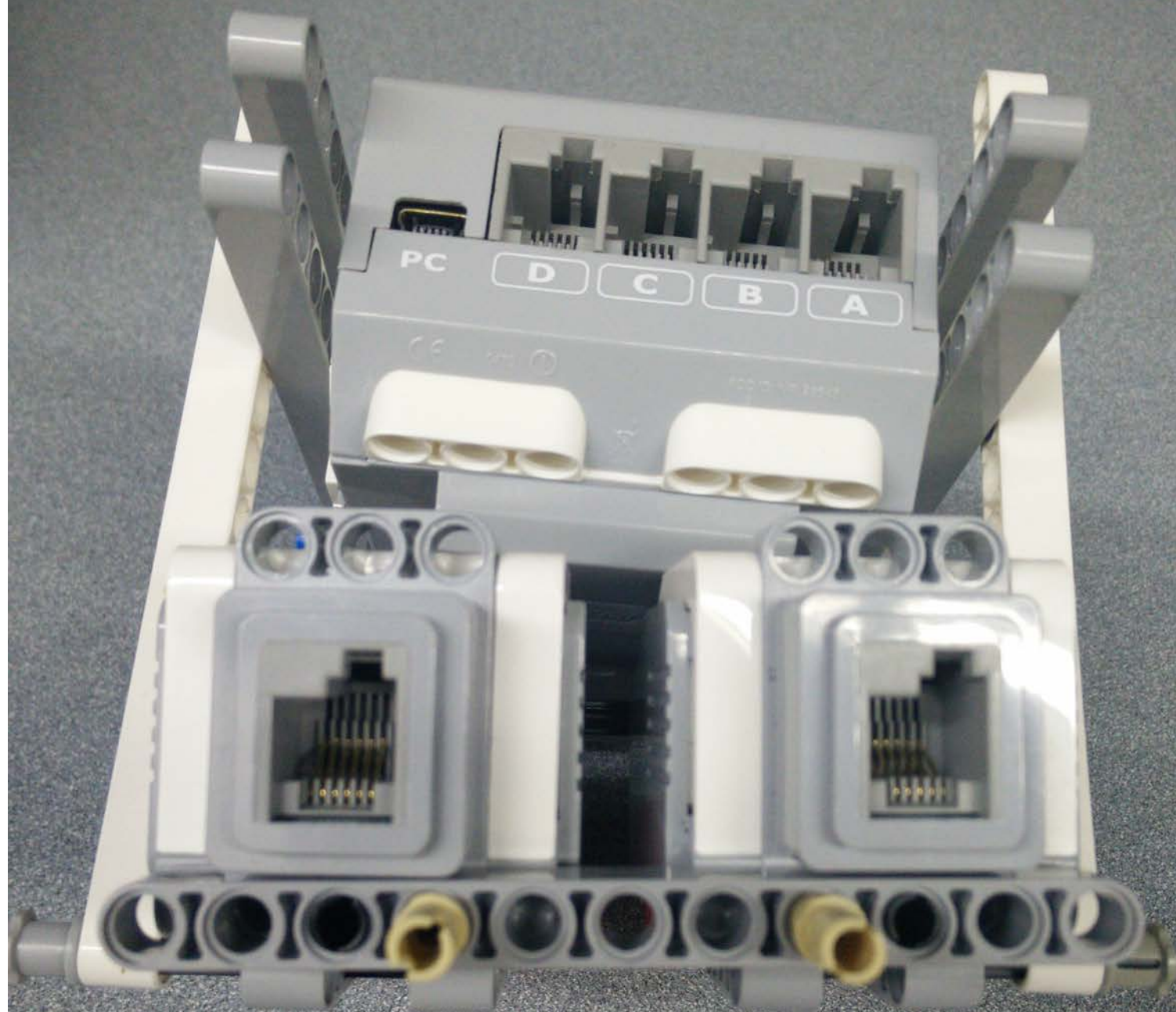


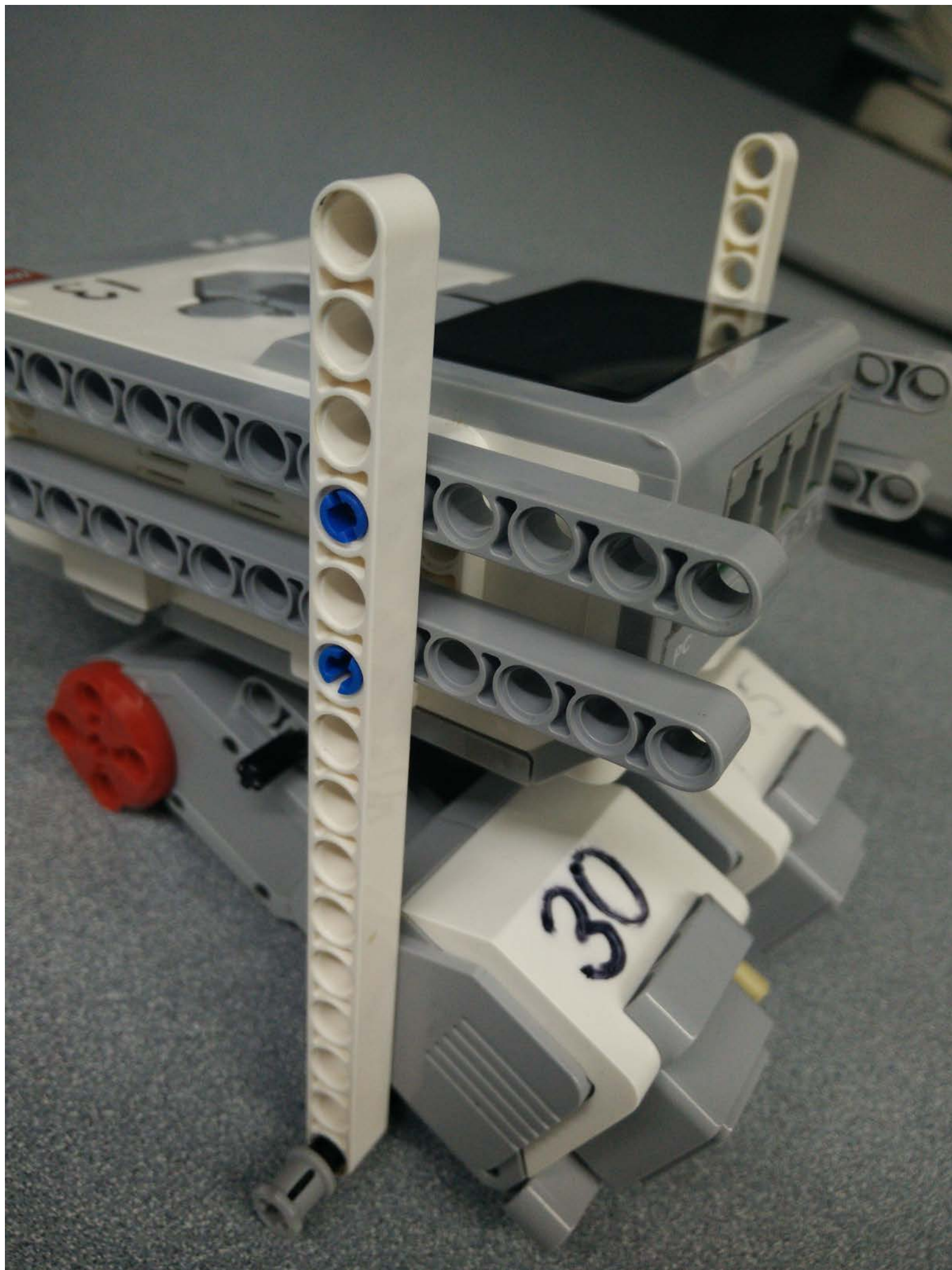


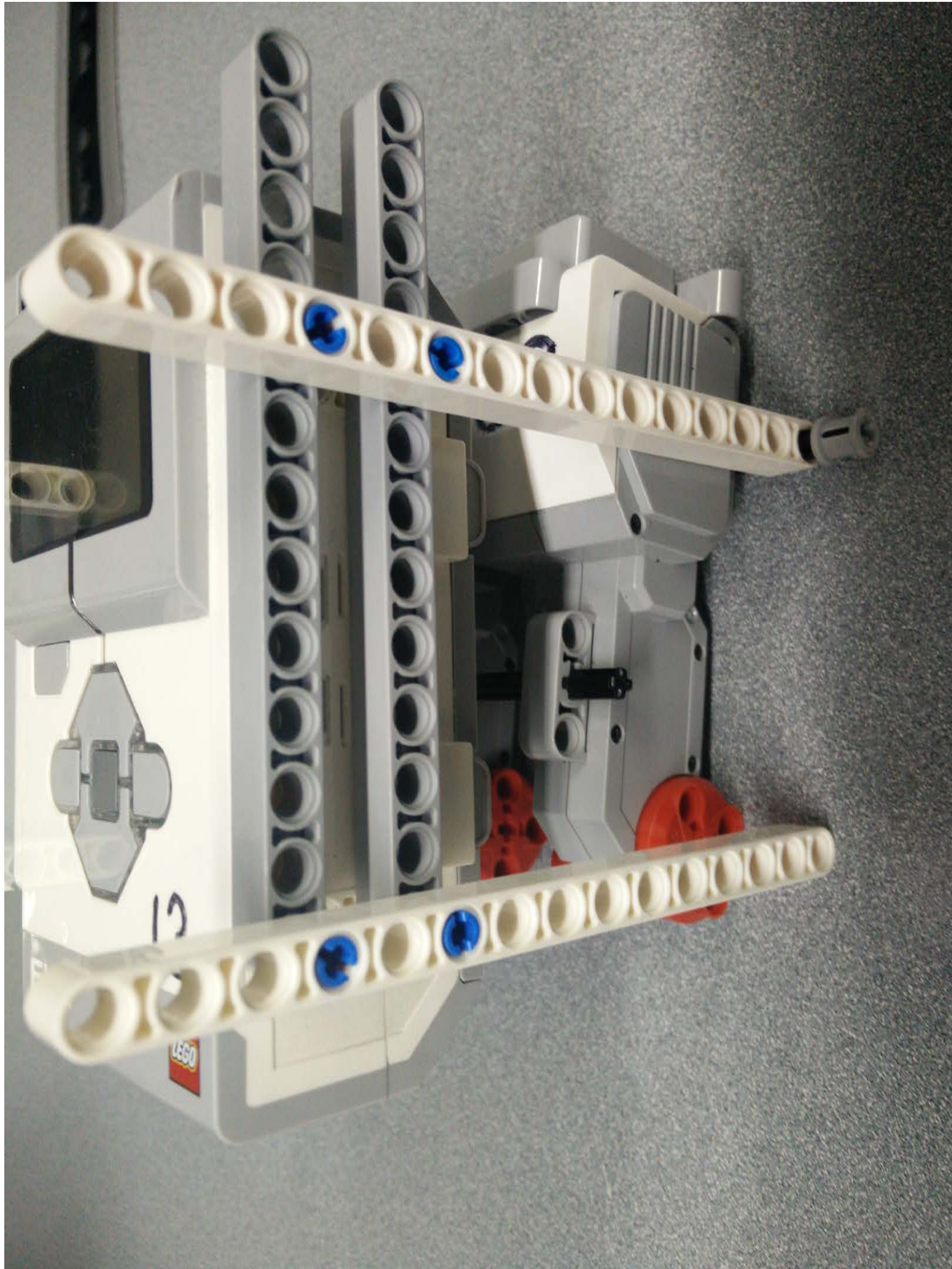




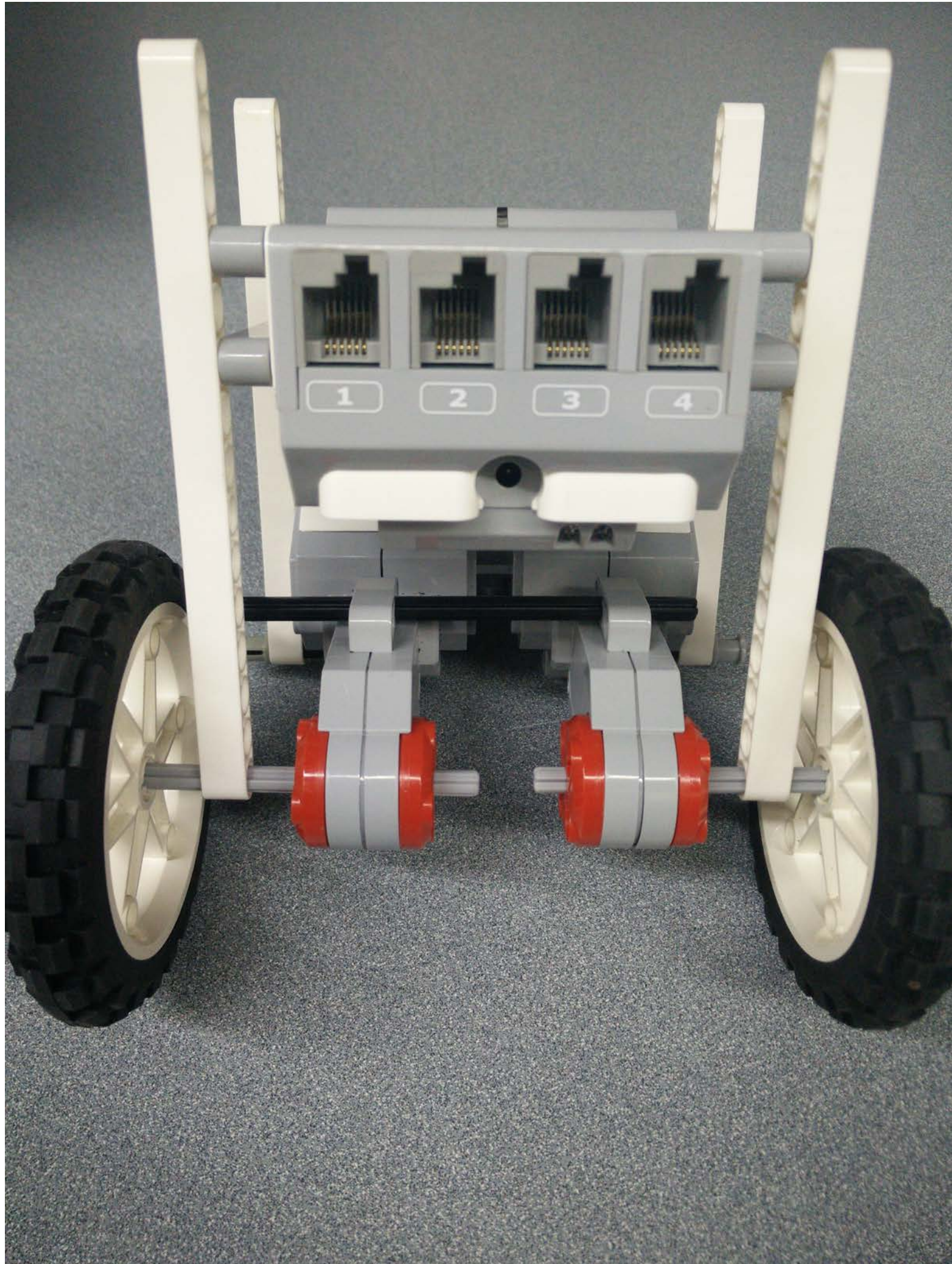


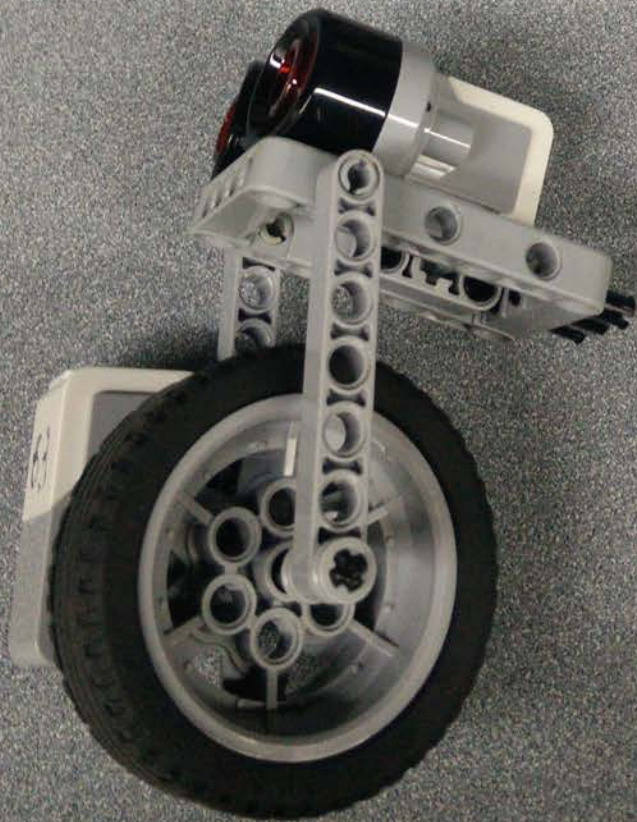


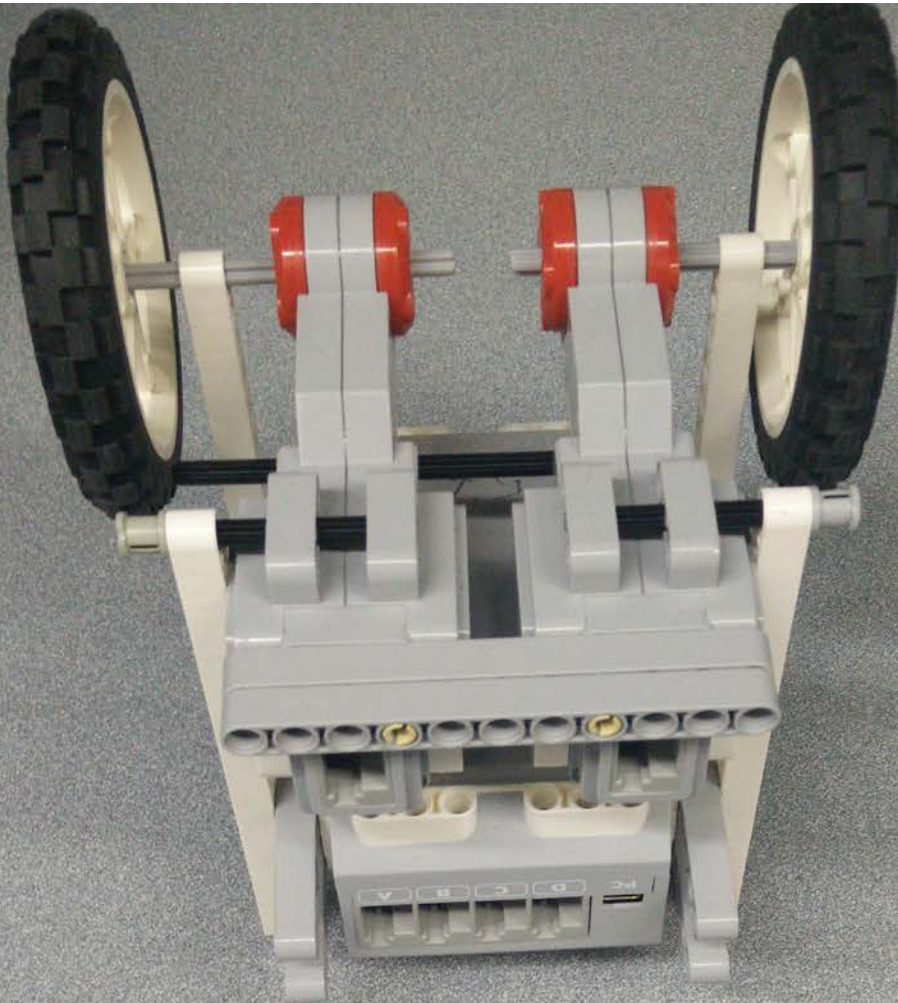


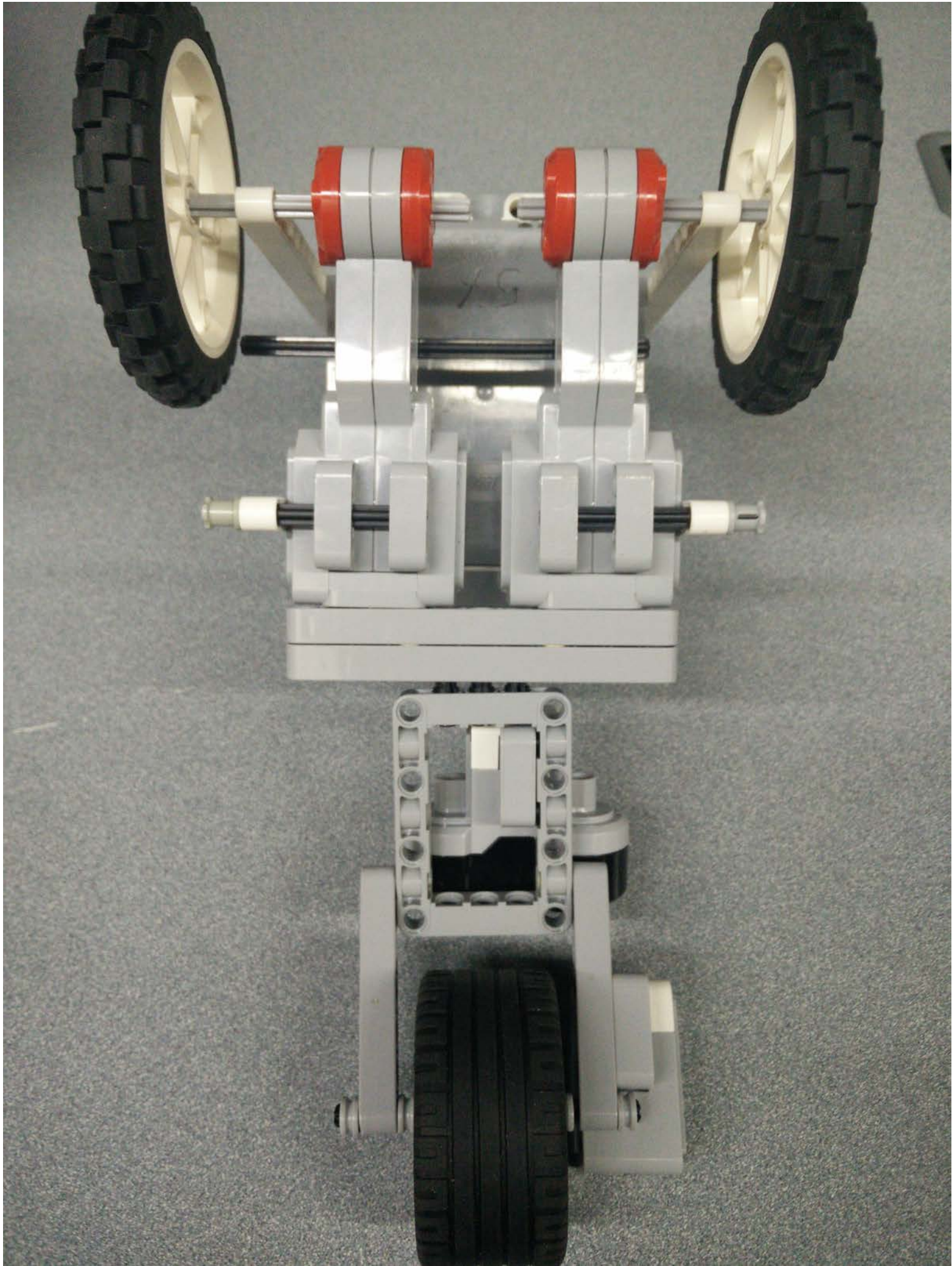


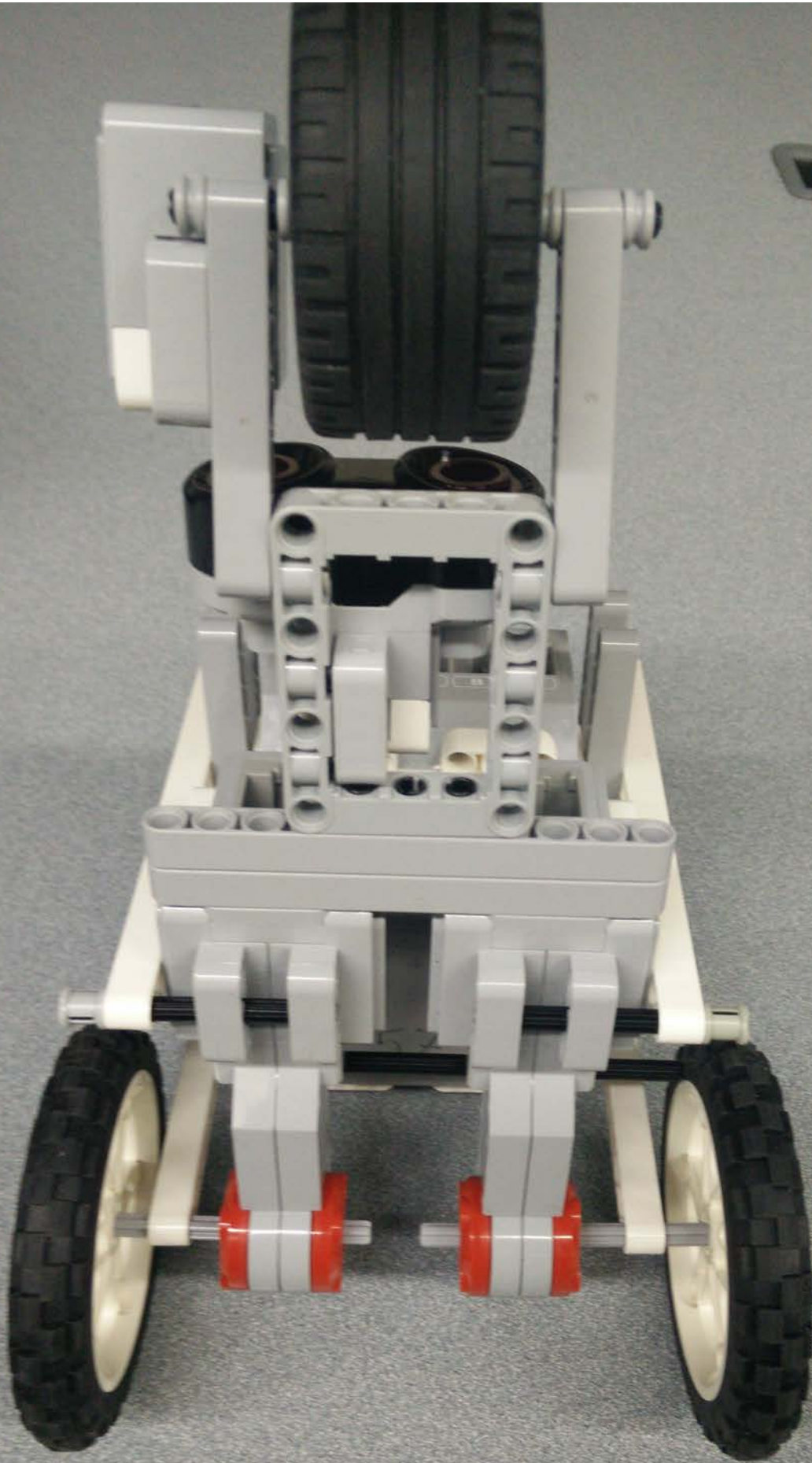


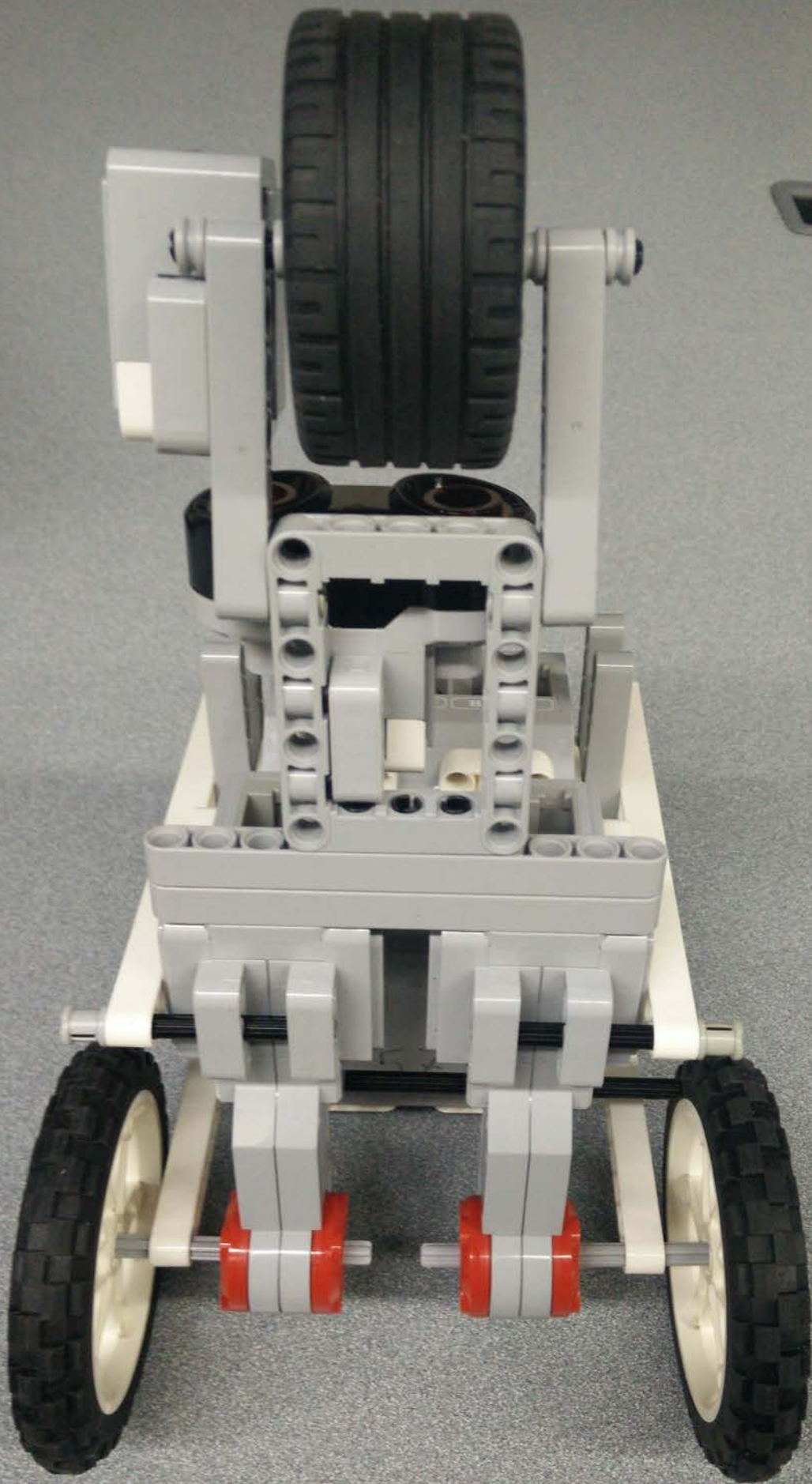


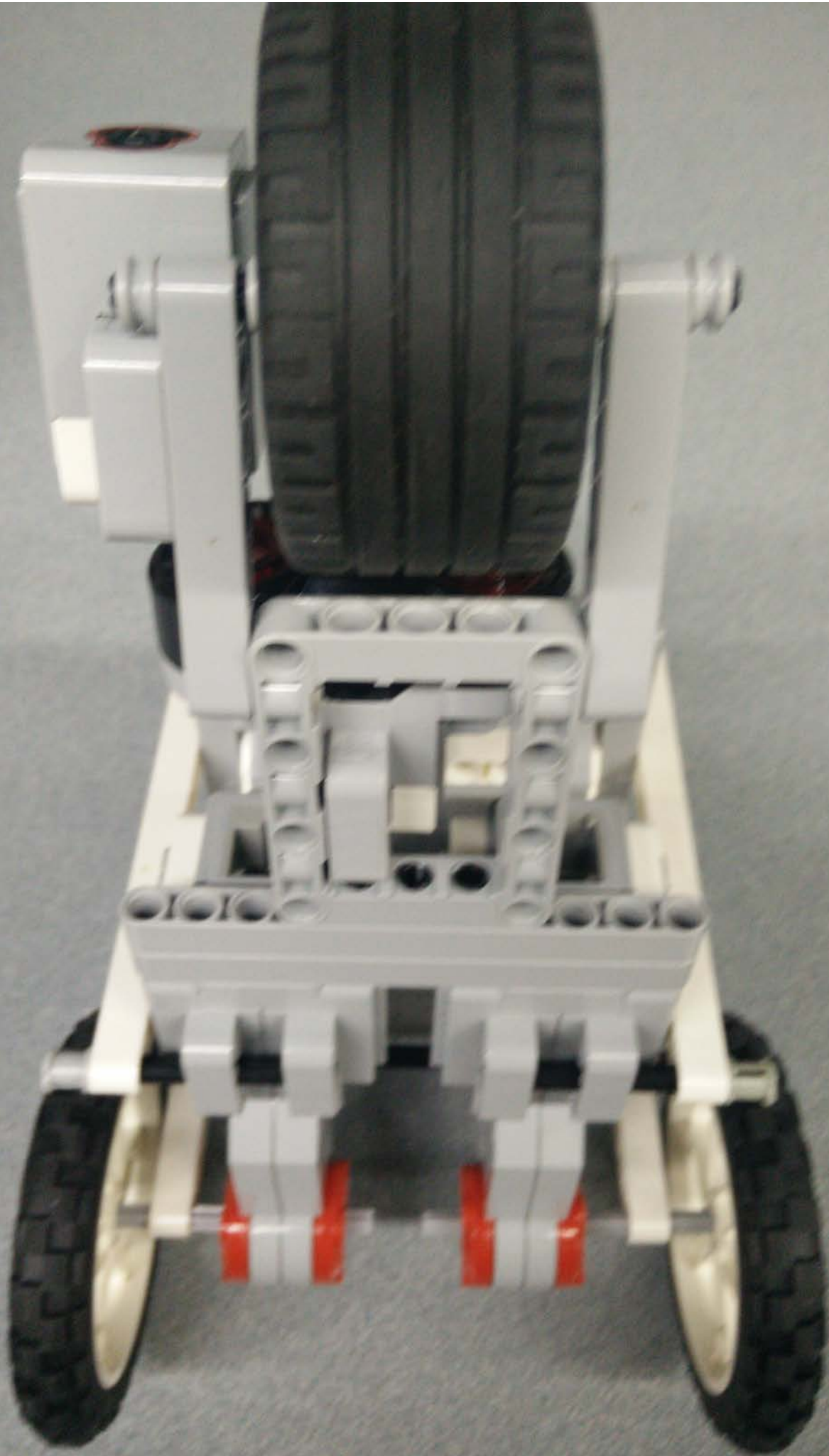


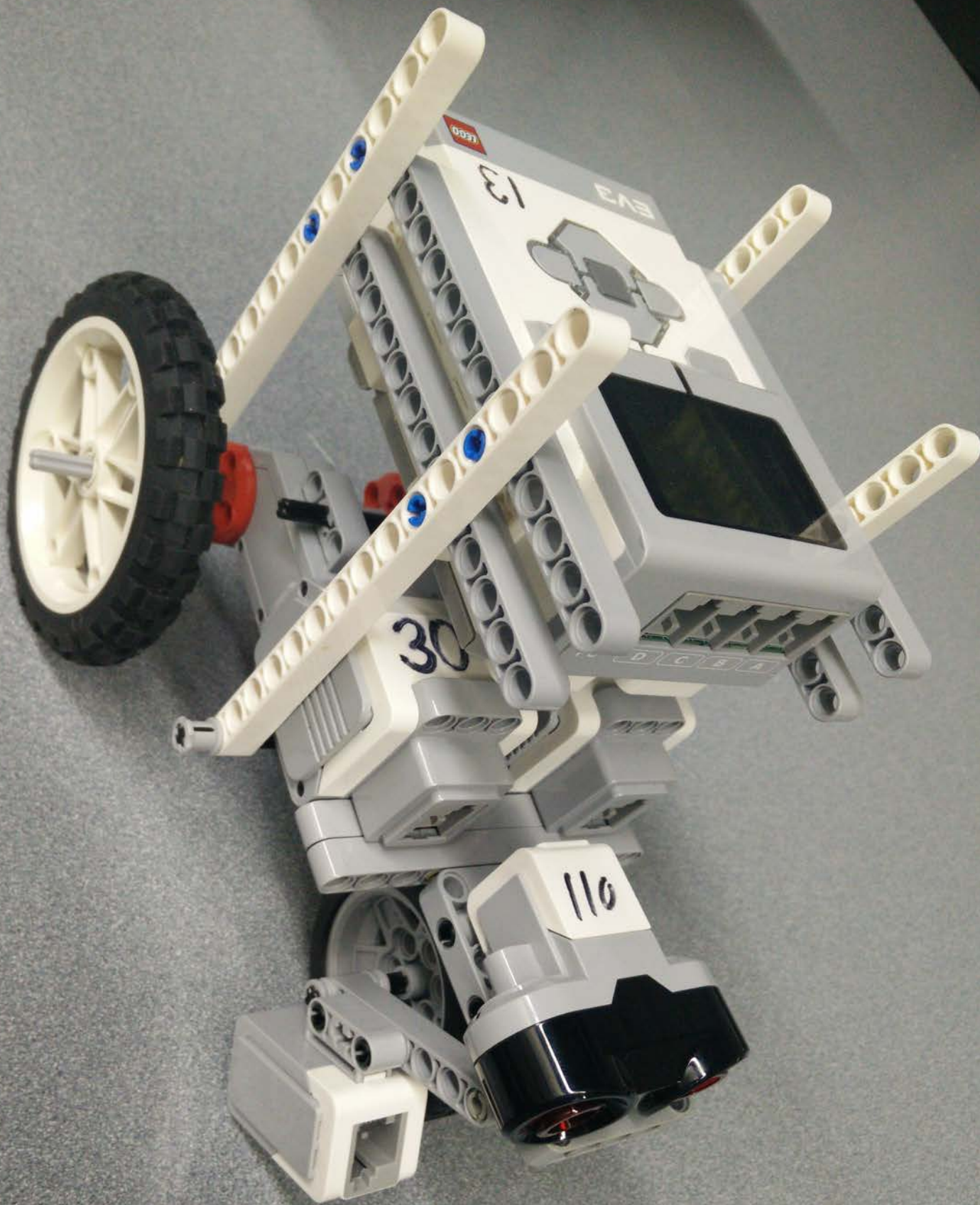


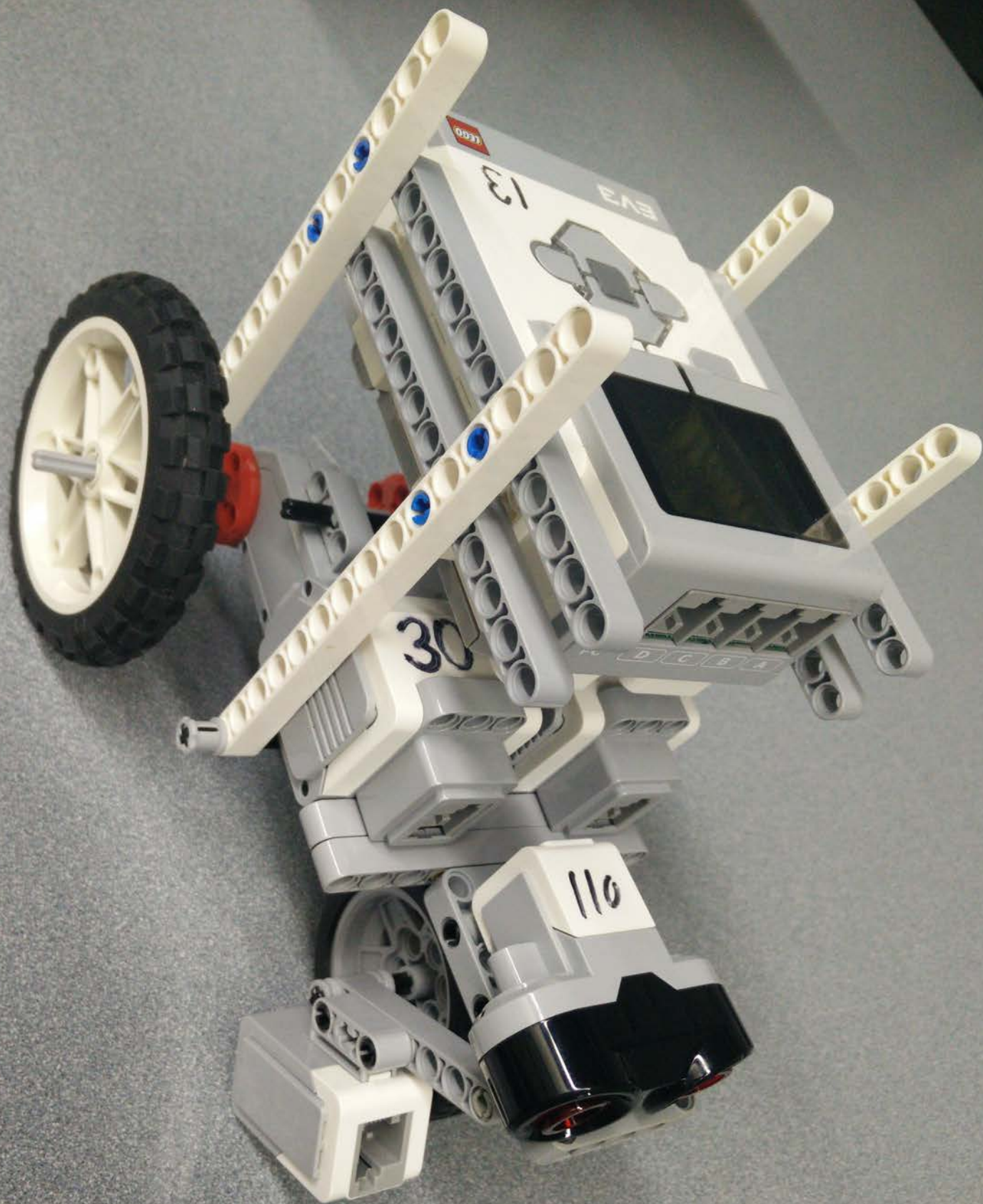














1. Attach the sensor cables to ports 1-4.
2. Attach the motor cables to ports A-D.

